**Chapter 5 Notes – Managing Risk with the IPDE Process**

IPDE is a system of \_\_\_\_\_\_\_\_\_, \_\_\_\_\_\_\_\_\_\_\_\_ and \_\_\_\_\_\_\_\_\_\_

Understanding Risk Factors: When you drive a car, you are at risk for accidents!

The Most Common Causes of Accidents

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***Identify:*** It’s more than just\_\_\_\_\_\_\_\_\_\_\_\_. Give \_\_\_\_\_\_\_\_\_\_\_\_\_\_ to what you see!

It’s all about knowing \_\_\_\_\_\_\_\_\_\_\_\_\_

The \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ allows you to manage the \_\_\_\_ zones of space surrounding your vehicle.

An \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ is the space you can drive free of restrictions to your line of sight

A \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ is the space NOT open because of a restriction in your line of sight such as a \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ or \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_. You need to find a new path.

**Three Searching Ranges**

#1:

#2

#3

**Aspect of Vision:**

Field of Vision:

Peripheral Vision:

Depth Perception:

Scanning:

**Predict:**

How to Predict: What to Predict:

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**Decide and Execute:**

Most Common Decision:

#1 #2 #3

**Lane Positions:**